

# Complete Xsens sensor fusion algorithm

- Compensation against long-lasting transient accelerations
- Ability to cope with GNSS outages
- Non-magnetic heading reference
- Tuned for performance under vibrations
- Selectable filter profiles for range of applications

# Best-in-class hardware design

- Highest quality industrial grade components
- Vibration-rejecting gyroscopes and accelerometers
- Built-in multi-GNSS receiver (GPS, GLONASS, BeiDou, Galileo) and barometer
- Wide array of (time) synchronization options

# Easy software integration

- Extensive suite of configurable output formats, calculated onboard the MTi-G-710
- MT Software Suite with intuitive GUI
- Complete SDK for all operating systems
- Support for Robotic Operating System (ROS)
- Xsens Xbus protocol or ASCII (NMEA)
- Access to BASE (by Xsens), an extensive knowledge base and community forum

# Specification highlights

- True North without requiring a magnetic field
- IP67 encased version or OEM board
- Choice of several interfaces and onboard USB
- All Xsens products are fully interchangeable
- Cost-effective system integrator solution
- Position, velocity and orientation outputs



IP67 (encased)

-40 to 85 °C

MIL-STD-202-201A/204C/214A

10 kHz/ch (60kS/s)

SyncIn, SyncOut, Clock sync 1 PPS



Up to 2 kHz

RS232/RS422/RS485/USB

<2 ms

1 ppm or external reference

Xbus or ASCII (NMEA)

Mounting orientation No restriction, full 360° in all axes

MTBF

300,000 hours

## **Product overview**

		MTi-G-710 GNSS/INS	
Calibrated Sensor Data	yes		
Roll/pitch	Static	0.2° 0.3°	
	Dynamic		
Yaw		0.8°	
Position and velocity			
Horizontal position	1 STD (SBAS)	1.0 m	
Vertical position	1 STD (SBAS, baro)	2.0 m	
Velocity accuracy	1 RMS	0.05 m/s	

All above specifications based on typical application scenarios



MTi 100-series Development Kit: MTi, software and cabling



MTi-G-710 encased: 57x42x23.5 mm, 55g, 9-pins push-pull connector



MTi-G-710 OEM: 37x33x12 mm, 11g, 16-pins header

# **Sensor specification**

		Gyroscop	oes	Ac	celerometers
Standard full range *		+/- 450 °/s		+/- 20 g	
Initial bias erro		0.2 °/s		5 mg	
In-run bias stability		10 °/h		15 µg	
Bandwidth (-3 dB)		415 Hz		375 Hz	
Noise density		0.01 °/s/√Hz		60 µg/√Hz	
g-sensitivity (calibrated)		0.003 °/s/g		N/A	
Non-orthogonality		0.05 deg		0.05 deg	
Non-linearity		0.01%		0.1%	
		Magnetom	neter		Barometer
Standard full range		+/-8G		300-1100 h	
Total RMS noise		0.5 mG		3.6 Pa	
Non-linearity		0.2%		N/A	
Resolution		0.25 m0	]	8 cm (sea level, 15 °C)	
	G	NSS receiver			
Receiver type	72-channel, 4 Hz GPS/QZSS L1 C/A, GLONASS L10F, BeiDou B1, SBAS L1 C/A: WAAS, EGNOS, MSAS		Horizontal accuracy (CEP)		2.0 m (SBAS) 2.5 m (Autonomou
Start-up time cold start	26 s		Velocity accuracy (@30 m/s)		0.05 m/s
Tracking sensitivity		-167 dBm			







### ABOUT XSENS

Xsens is the leading innovator in 3D motion tracking technology and products. Its sensor fusion technologies enable a seamless interaction between the physical and the digital world in applications such as industrial control and stabilization, health, sports and 3D character animation. Clients and partners include Electronic Arts, NBC Universal, Daimler, Autodesk, ABB, Siemens and various other leading institutes and companies throughout the world. Xsens is part of mCube, the provider of the world's smallest MEMS motion sensors, key enablers for the Internet of Moving Things. Xsens has offices in Enschede, Los Angeles, Shanghai and Hong Kong.

Visit xsens.com/distributors for an overview of Xsens' worldwide distributor network



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